# Online Study Design Tool for Offshore Automated Radio Telemetry Stations

Please rename yourself as "First and Last Name, Affiliation" by hovering over your name in the "Participants" tab and clicking Rename

# Stakeholder Workshop January 13, 2021









### **Project Team**

USFWS Migratory Birds: Pam Loring, Scott Johnston

**Biodiversity Research Institute:** Kate Williams, Andrew Gilbert, Evan Adams, Julia Gulka, Ed Jenkins

Univ. of Rhode Island: Peter Paton, Doug Gobeille, Erik Carlson, Rob Deluca

Birds Canada: Stu Mackenzie

NYSERDA (funding): Kate McClellan Press, Gregory Lampman









## Zoom controls

• Please rename yourself as "First and Last Name, Affiliation" by hovering over your name in the Participants tab



# Zoom controls

Please mute yourself when you are not speaking
Use the chat box and raise hand functions (or feel free to unmute and talk if that makes the most sense in the moment)



# Agenda

- 10:00-10:10 introductions
- 10:10-10:15 overview: project components, goals for study design tool
- 10:15-10:35 capabilities and limitations of Motus technologies
- 10:35-10:55 what questions do we want to ask with Motus in the offshore environment?
- 10:55-11:00 coffee break
- 11:00-11:55 study design tool demo and discussion
- 11:55-12:00 next steps

### **Overall project goal:**

To develop standardized protocols for using automated radio telemetry to monitor bird and bat movements at offshore wind energy areas throughout the U.S. Atlantic.



### **Overall Project Components**

- Monitoring Framework tags and study design
- **Guidance Document** offshore receiving stations
- Online Study Design Tool map detection coverage
- Simulation Study model animal movement data
- Motus Data Framework centralized portal for data management, coordination, and summary reports

## **Objectives of Online Study Design Tool**

- Develop a free online tool to help optimize site-specific study designs at offshore wind projects
- Input data:
  - Birds flight height, taxa, movement/distribution patterns
  - Wind project area, number & locations of potential receiver locations (turbines, substations, met tower)
  - Antenna data type, height, gain, frequency
- Outputs:
  - Map of antenna coverage for station
  - Optimization for % coverage, % simultaneous detections, etc.
  - Study design report output TBD

### **Automated Radio Telemetry:**

- Radio transmitters: "tags" attached to birds and bats, emit signals on a shared frequency
- Receiving stations: antennas and data-logger that monitors shared frequency and records detections of "tagged" birds or bats flying by
- Motus Wildlife Tracking System: international network of collaborative automated radio telemetry studies

## **Motus Wildlife Tracking System**

- Central hub for detection data and metadata
- > 900 collaborators across four continents
- > 900 tracking stations
- > 25,000 animals tagged
- >200 species





### **Operating Frequencies**

Two different frequencies on Motus Network

- 166 MHz (original frequency)
- 434 MHz (new frequency)

Previous studies used 166 MHz (2012 – 2019)

- Good detection range (5-15 km) from Yagi (directional) antennas, but need long antennas (e.g. 11 dB gain = 10 ft antennas)
- High electromagnetic interference in marine environments (boats, etc.)

Currently field testing 434 MHz

- Higher frequency = smaller antennas for same amount of gain
- 434 MHz Yagi with 11 dB gain = 3.25 ft

### Strengths of automated radio telemetry:

- Light-weight tags (range: 0.2 to 3 g) suitable for small-bodied species
- Thousands of uniquely identifiable tags shared frequency large sample size leveraged by Motus (centralized data hub)
- Tags transmit every 5 seconds (high temporal resolution)
- Receiving stations continuously monitor presence of tagged animals within detection range, around the clock, and during all types of weather conditions
- Data from antennas at multiple receiving stations detecting the same animal at the same time can be used to model coarse estimates of flight paths and altitude (methods are under development)

### Limitations of automated radio telemetry:

- Tag detections limited to antenna coverage of receiving stations
- Various factors affect antenna coverage: antenna type, gain, number, height, and configuration; flight height of tagged animals
- Antennas do not work very well for detecting birds sitting on water (signal scatter) best for tracking flights
- Metal or other objects between antennas and surrounding airspace will reduce or block tag detections
- Electromagnetic interference may reduce antenna coverage
- Due to site-specific variation in antenna coverage, important to ground truth antenna coverage of tracking stations using a test tag at various altitudes and distances from receiving antennas







Loring PH, Paton PWC, McLaren JD, Bai H, Janaswamy R, Goyert HF, Griffin CR, Sievert PR. 2019. Tracking Offshore Occurrence of Common Terns, Endangered Roseate Terns, and Threatened Piping Plovers with VHF Arrays. Sterling (VA): US Department of the Interior, Bureau of Ocean Energy Management. OCS Study BOEM 2019-017.

### **Example Applications of Motus Technology With Stations in Project Area**

- Presence of focal species (e.g. ESA-listed Piping Plover, Red Knot, Roseate Tern) within project area (with targeted tagging efforts)
- Inputs to collision risk models (passage rates, day vs. night, weather conditions) - currently under development
- Opportunistic monitoring of species tagged by Motus network collaborators that may pass through project area
- Movements of tagged animals between stations in different project areas throughout the U.S. Atlantic, in coordination with Motus
- Analyses of flight paths and altitude possible with sufficient antenna coverage (simultaneous detections from multiple stations) and modeling tools methods currently under development



- Example of the intersection the simultaneous detections by receiving antennas from two separate towers
- Red x represents the approximate location of the bird

Paton PWC, Cooper-Mullin, C., Kouhi, S. Loring PH, Moore J, Miller J, Potty G. 2021. Assessing movements of birds using digital VHF transmitters: A validation study. Sterling (VA): US Department of the Interior, Bureau of Ocean Energy Management. OCS Study BOEM 2021-009. 222 p.

#### Alternative technologies: Satellite/GPS

- Global tracking coverage via satellite
- In example Common Terns tracked with 2-g Argos PTT tags, avg 11 locations per day. Spatial error of locations <250 - >1,500 m
- Spatial and temporal resolution varies with size of tag (battery)
- Heavier GPS tags (larger-bodied birds) higher spatial and temporal resolution
- GPS technology complementary to Motus help fill in data gaps
- Larger birds (e.g. gulls, gannets) can be doubletagged with GPS and Motus tags
  - Movement data at multiple scales
  - Useful for ground-truthing antenna coverage of Motus stations
  - Field work at Block Is to test on gulls this spring



# Stakeholder Meeting: Study Design

Evan Adams Goals for offshore automated telemetry studies 1/13/2021



# Automated Telemetry Offshore

- Researchers have begun to use automated telemetry to determine occupancy and flight paths for marine birds
- Telemetry receivers have mostly been placed on coastal lands
- As offshore wind buildout begins, we will have new option for distributing receivers



# What kinds of questions are we interested in answering offshore?

- Large-scale questions
  - Occupancy
    - Are individuals present in a study area?
    - Key metrics: frequency of study area use, proportion of sampled population using the study area
    - Receiver placement should consider the area that we want to confirm occupancy

# What kinds of questions are we interested in answering offshore?

- Large-scale questions
  - Macro-avoidance
    - Are animals avoiding the turbine footprint?
    - Before/after comparisons are not usually possible
    - Receiver placement after construction will be key to detemining if the animal was inside the study area
    - Proximity to the turbine footprint is not likely measurable

# What kinds of questions are we interested in answering offshore?

- These questions rely on more accurate position estimation, which is an area of ongoing research
  - Generally, we should be cautious about assuming that accurate positions can be estimated with automated telemetry
  - To estimate flight paths, we need an accurate estimate of flight height
  - Perhaps we can make some reasonable assumptions to get us out of this identifiability issue
- Small-scale questions that telemetry could help with
  - Flight height estimation
  - Space/Habitat-use
  - Meso-scale avoidance
- Small-scale questions that telemetry would not be helpful with:
  - Micro-avoidance
  - Collisions

How effective are offshore receivers for answering key questions for marine species?

- This likely depends on the:
  - Goals of the study
    - Are you interested in estimating occupancy in an area or habitat use? These goals require very different scales of information
      - Single antenna v. multi-antennae detections
  - Study design
    - How many receivers are used and in what spatial configuration?
    - Transmitter configuration
  - Study species
    - How do species move through the environment?
    - What height to they typically fly?
    - Do they spend a lot of time resting on the water?





Average Flight Height = 100 m



Detection Threshold = -68.1 dbm

# Discussion

- Are there other kinds of questions you are interested in answering with automated telemetry?
- How effective is automated telemetry in answering these questions relative to other kinds of methods?
- What other aspects of study design should we consider?

# Online Study Design Tool for Offshore Automated Radio Telemetry Stations

Andrew Gilbert

# Stakeholder Workshop January 13, 2021





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#### Automated Telemetry Study Design Tool

Study area data

determined by 360°/antenna number.

5) Click "Generate Array Button".

Instructions

Detection results

4) Modify receiving station parameters and detection parameters.

Study design report

#### 1) Study area and array

Design a study
Opload a study

Add default study Remove study

#### 2) Input parameters

- '☆' Receiving Station Params <</p>
- 🔹 Detection parameters

#### 3) Detection array creation

- **Optimization type:**
- None (manual selection)Coverage optimized
- Density optimized
- Avoidance optimized

Generate array



1) Upload a study area outline and possible antenna station locations as shapefiles or create a wind farm using parameters in the "Create a wind farm" parameters sidebar option. 2) Select (deselect) locations for proposed MOTUS antenna arrays by either clicking station points on the map or the table. Stations will be added to the selected stations table.

3) Modify default starting antenna angle of proposed (or actual) antenna angles by editing the "Starting antenna angle" column of the Selected Stations table. All other antennas will be assumed to be equally spaced with antenna spacing being

#### Selected stations

#### v0.53 - Ground Sloth 🜍 🙀

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#### Station data



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2) Input parameters

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	ID 🔶	Latitude 🔷	Longitude
34	34	41.47057	-70.3380
35	35	41.47057	-70.3201
36	36	41.47057	-70.3021
37	37	41.47057	-70.2841
38	38	41.47057	-70.2662
39	39	41.47057	-70.2482
40	40	41.47057	-70.2302
41	41	41.47057	-70.2123
42	42	41.47057	-70.1943
43	43	41.47057	-70.1763
49	49	41.48403	-70.3380
50	50	41.48403	-70.3201
51	51	41.48403	-70.3021
52	52	41 48403	-70 2841

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### Input parameters







### 3) Detection array creation

#### **Optimization type:**

- None (manual selection)
- Coverage optimized
- Density optimized
- Avoidance optimized

Detection polygon color

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Generate array

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Detection parameters

**Optimization type:** None (manual selection) Coverage optimized

Density optimized Avoidance optimized Generate array

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#### Selected stations

	ID	Latitude	Longitude	First antenna angle
50	50	41.48400	-70.32010	45.0
58	58	41.48400	-70.17640	270.0
96	96	41.52440	-70.30220	120.0
102	102	41.52440	-70.19440	30.0

	ID 🔶	Latitude 🍦	Longitude
43	43	41.47057	-70.1763
49	49	41.48403	-70.3380
50	50	41.48403	-70.3201
51	51	41.48403	-70.3021
52	52	41.48403	-70.2841
53	53	41.48403	-70.2662
54	54	41.48403	-70.2482
55	55	41.48403	-70.2302
56	56	41.48403	-70.2123
57	57	41.48403	-70.1943
58	58	41.48403	-70.1763
64	64	41.49749	-70.3380
65	65	41.49749	-70.3201
66	66	41.49749	-70.3021

Computing data completed 185 m step 8 of 8 flight heights, at: 2021-01-13 07:48:33, elapsed time: 0.1 minutes

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Detection parameters

#### 3) Detection array creation

#### **Optimization type:**

- None (manual selection)
- Coverage optimized
- Density optimized
- Avoidance optimized

Generate array

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Flight height (m) 🌲	Max detection range (m) 崇	Study area covg. 🌲	Antenna coverage overlap 🌲	Min. covg. flag 🌲
1 10				0
2 35	9,116	1.00	0.41	1
3 60				1
4 85	14,006	1.00	0.48	1
5 110				1
6 135				1
7 160				1
8 185	20,016	1.00	0.51	1
			Co	mputing data completed 185 m step 8

of 8 flight heights, at: 2021-01-13 07:48:33, elapsed time: 0.1 minutes

1	50	45
2	50	135
3	50	225
4	50	315
5	58	0
6	58	90
7	58	180
8	58	270
9	96	30
10	96	120
11	96	210

theta 🔶

Station antenna angles

station



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25	Station anten	na angles	
lax. detection flight height 🛛 🔇		station 🔶	theta 🔶
50	1	1	45
50	2	1	135
ght height detection increment	3	1	225
25	4	1	315
25	5	2	0
	6	2	90
tection array creation	7	2	180
imization type:	8	2	270
Ione (manual selection)	9	3	30
Coverage optimized	10	3	120
Density optimized Avoidance optimized	11	3	210

3) Detection arr

Avoidance op

Tag detection data											
	Flight height (m) 🍦	Max detection range (m) 🍦	Study area covg. 🍦	Antenna coverage overlap 🍦	Min. covg. flag 🌲						
1	25	7,726	0.19	0.22	0						
					0						

Computing data completed 50 m step 2

of 2 flight heights, at: 2021-01-13 09:23:52,

elapsed time: 6.7 minutes

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# Discussion

- What would you like for inputs?
- What would you like for outputs?
- Layout changes?
- Needs for the report tab?
- Study designs that are not captured here that could be implemented in tool?
- Would you like to be a beta tester?
  - If so email me (Andrew Gilbert, Andrew.Gilbert@briloon.org) and/or Kate Williams (<u>Kate.Williams@briloon.org</u>) to be added to the working group to provide further info and be sent the link to the app